Bayesian Hierarchical Models for the Prediction of A **American Elections**

Abstract

We propose a series of hierarchical Bayesian models to predict the outcome of American elections using only toplines from preelection polling. The models are applied to recent federal elections with a focus on the past three Presidential elections. The models are structured to allow the pooling of information between states deemed similar. The models are similarly structured but they have different distributional assumptions (i.e. Gaussian) and likelihood structures. They are based on previous models that were found to be approximately 93% as accurate as the FiveThirtyEight Polls Plus model in terms of RMSE in predicting the 2008, 2012, and 2016 presidential elections and made nearly identical predictions of the winners of states as FiveThirtyEight. These models also were more accurate than averaging the polls. The methodology is implemented in the forthcoming bayesurvey R package and will be implemented to predict the 2020 Presidential and senate elections..

Previous Work

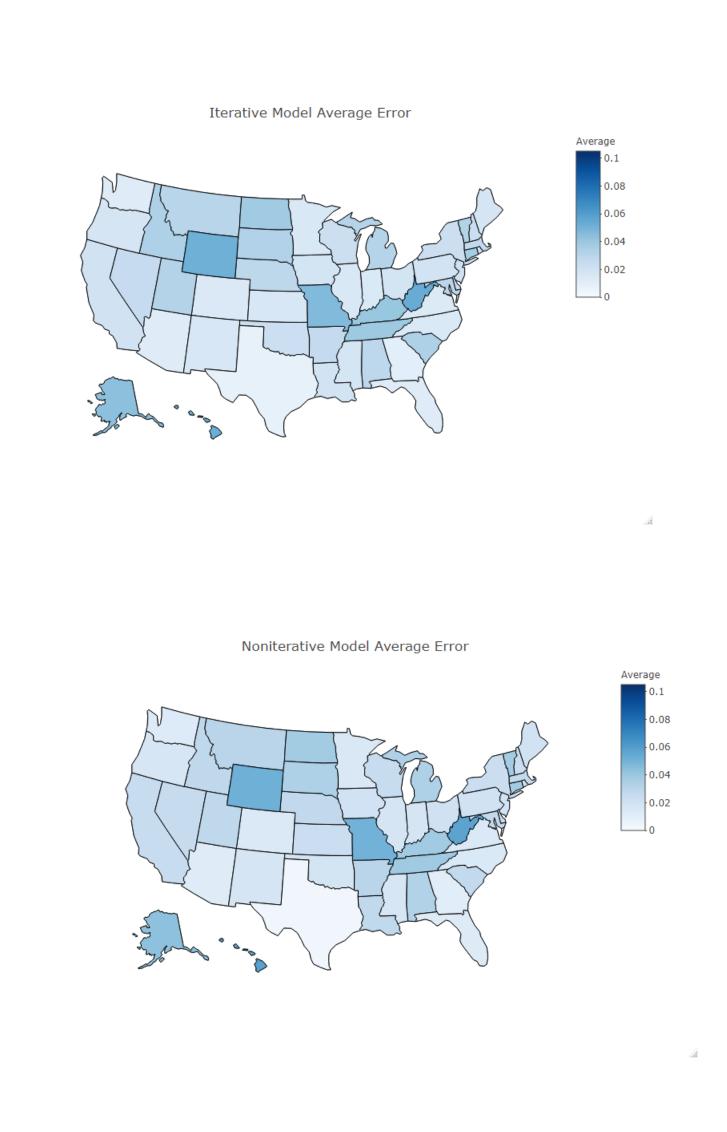
- Alexander & Ellingson (2019) created a series of Bayesian conjugate prior models for predicting the two party support for the 2008, 2012, and 2016 American Presidential election
- Data source was Huffington Post's Pollster
- Bayesian modelling uses prior information and that prior information comes from clustering states in those models
- States are clustered into groups based on the average margin from the past four elections
- The cutoffs for groups are -.2, -.1, -0.025, 0.025, .1, .2 with states in the group where the average margin was between the two points
- Alexander & Ellingson (2019) only considered polls after July 1st This projects uses the Iterative Gaussian (updates with every poll) and noniterative gaussian model (fit once)
- Poll and election data was proportionally normalized so that the sum of the Democratic and Republican support was equal to 1
- Iterative model updates for every poll, noniterative averages the polls and updates once

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New Method

- Includes a new model that predicts the Democratic and Republican support)
- A Rolling average model using the last
- The best performing rolling average mo and was rounded to 10 for simplicity
- Fit models using only the last 60 days of
- Included iterative model that used provi estimate variance instead of standard er
- 60 days is when polls error starts decrea
- These models are now implemented in t (available on Github as beta version) ar instantaneously fit
- DC is removed from average error calcu outlier that in recent elections has alway for the Democratic than the vote in any
- A state is called competitive is it's marg



References

B. Alexander, Leif Ellingson, "Poll-Based Bayesian Models to Predict United States Presidential Elections". Joint Statistical Meetings Proceedings 2019. 112-131 ¹Christensen, W. F., & Florence, L. W. (2008), January 1). Predicting Presidential and Other Multistage Election Outcomes Using State-Level Pre-Election Polls. The American *Statistician, 62*(1), 1-10. doi:10.1198/000313008x267820

Five Thirty Eight. (2016). [Data] available from http://fivethirtyeight.com

Huffington Post. (2016). Pollster [Data] available from http://elections.huffingtonpost.com/pollster

hargin (difference in -25 polls were test els used about 8-12 polls		Iterative Gaussian Model	Iterative Gaussian with Variance from MOE Model		Noniterative Gaussian (Margin) Model	Noniterative Gaussian (Margin) Model Normalized	Avera of All Polls
polling or using all polls	All Polls	0.026	0.031	0.026	0.055	0.049	0.025
ed margin of error to	Rolling	0.025	0.030	0.026	0.054	0.048	0.025
of a proportion	Average Last 60 days	0.027	0.029	0.026	0.053	0.048	0.025
ng over time bayesurvey R package can be almost	All Polls Competitive States	0.014	0.015	0.015	0.027	0.029	0.013
tion because it is an	Rolling Average Competitive States	0.017	0.017	0.019	0.036	0.038	0.013
had significantly support ner states is between -5 and 5.	Last 60 days Competitive States	0.012	0.014	0.013	0.023	0.025	0.013
Iterative Model using MOE Average Error			Dis	cussi	on		

- tested to see if it improves error
- clusters
- election

Normalized Margin Model Average Error

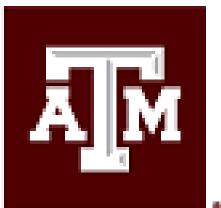


• More cutoff dates for including polls should be tested

Combining a rolling average with a cutoff date should be

• The use of previous election results could be a potential new source of prior information that could be combined with the

Bayesian Methods show promise to predict elections These models have an tendency to underestimate the uncertainty and historical model performance should be considered when evaluating the uncertainty in the 2020



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